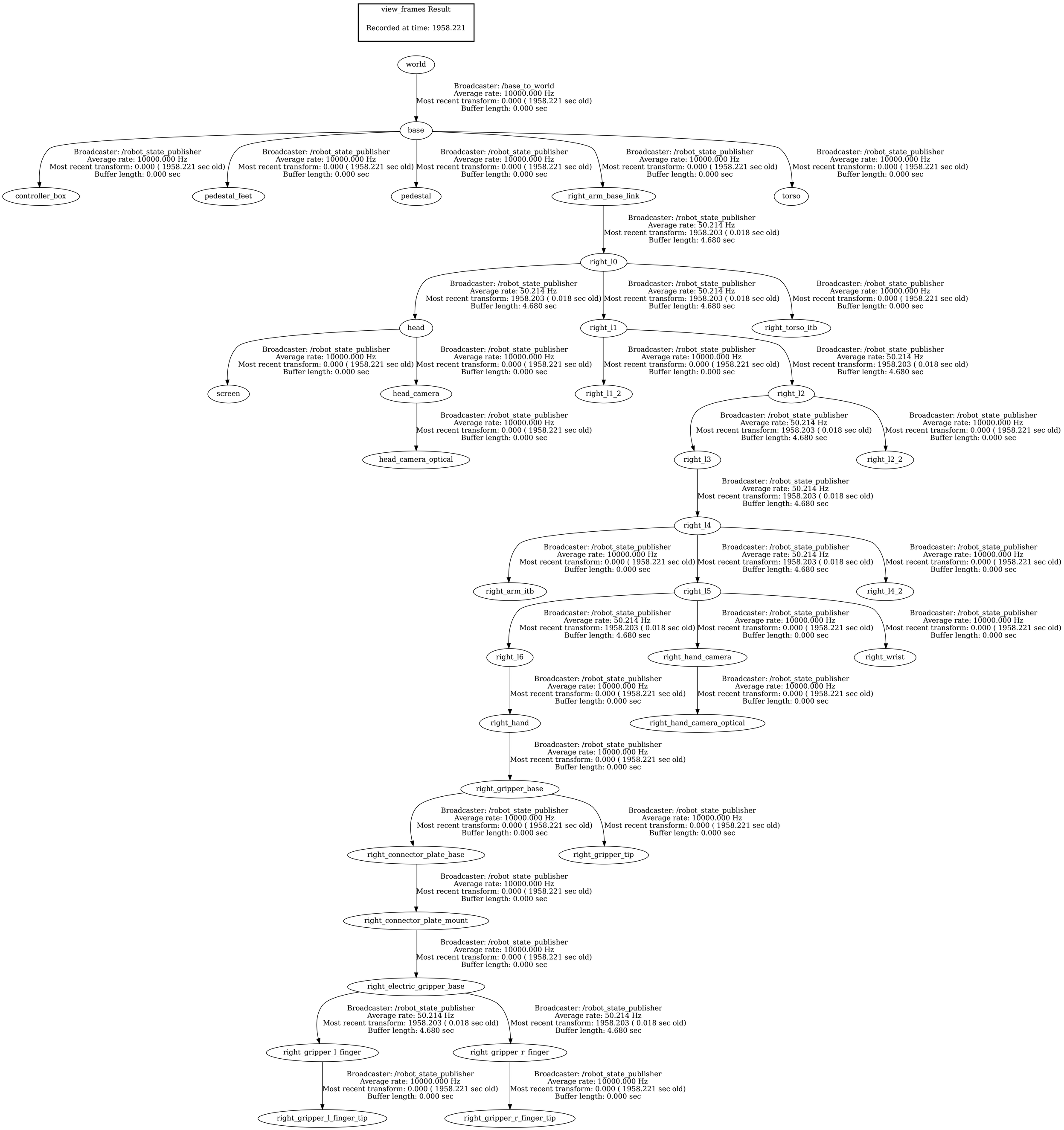
view_frames Result
Recorded at time: 1958.221
world
Broadcaster: /base_to_world
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1958.221 sec old)
Buffer length: 0.000 sec
base
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1958.221 sec old)
Buffer length: 0.000 sec
controller_box
pedestal_feet
pedestal
right_arm_base_link
torso
Broadcaster: /robot_state_publisher
Average rate: 50.214 Hz
Most recent transform: 1958.203 (0.018 sec old)
Buffer length: 4.680 sec
right_l0
head
right_l1
right_torso_itb
screen
head_camera
right_l1_2
right_l2
head_camera_optical
right_l3
right_l2_2
right_l4
right_arm_itb
right_l5
right_l4_2
right_l6
right_hand_camera
right_wrist
right_hand
right_hand_camera_optical
right_gripper_base
right_connector_plate_base
right_gripper_tip
right_connector_plate_mount
right_electric_gripper_base
right_gripper_l_finger
right_gripper_r_finger
right_gripper_l_finger_tip
right_gripper_r_finger_tip